

# Simultaneous Controllability for a System with Resistance Term

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**Abstract.** In this work we study the simultaneous controllability for a system of equations that constitutes a model of dynamical elasticity for incompressible materials.

## 1. Introduction

Let  $\Omega$  be a bounded domain of  $\mathbb{R}^n$  with regular boundary  $\Gamma$ . Let  $Q$  denote the cylinder  $\Omega \times (0, T)$  whose lateral boundary is given by  $\Sigma = \Gamma \times (0, T)$ .

In this work, we shall consider the simultaneous controllability for the system

$$\left\{ \begin{array}{ll} y_1'' - \Delta y_1 = -\nabla p & \text{in } Q \\ y_2'' - \Delta y_2 = -\nabla q & \text{in } Q \\ \operatorname{div} y_1 = 0 & \text{in } Q \\ \operatorname{div} y_2 = 0 & \text{in } Q \\ y_1 = v & \text{on } \Sigma \\ \frac{\partial y_2}{\partial \nu} = w & \text{on } \Sigma \\ y_1(0) = y_1^0, y_1'(0) = y_1^1 & \text{in } \Omega \\ y_2(0) = y_2^0, y_2'(0) = y_2^1 & \text{in } \Omega \end{array} \right. \quad (1.1)$$

where  $p = p(x, t)$  and  $q = q(x, t)$  denote the resistance terms.

Physically the above system models the small deformations or displacements of the solid body  $\Omega \subset \mathbb{R}^n$  composed of incompressible elastic materials, subject to controls acting on the boundary  $\Sigma$ .

The simultaneous controllability for the system (1.1) is formulated as follows: given  $T > 0$  large enough, find a Hilbert space  $H$  such that for every set  $\{y_1^0, y_1^1, y_2^0, y_2^1\}$  belonging to  $H$ , there exists a pair of controls  $\{v, w\}$ , such that a solution  $\{y_1(v), y_2(w)\}$  of (1.1) satisfies the equilibrium condition

$$y_1(T) = y_1'(T) = y_2(T) = y_2'(T) = 0, \quad (1.2)$$

and

$$w = \frac{\partial v}{\partial t} \quad \text{on } \Sigma.$$

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We investigate this problem by means of the Hilbert Uniqueness Method (HUM) idealized by Lions [6].

The problem of the simultaneous controllability was initially studied by Lions [6]. Kapitonov [4] investigated a similar question. For exact controllability we mention Cavalcanti et al [2].

## 2. Notations, Assumptions and Results

We consider  $\Omega_0, \Omega_1 \subset \mathbb{R}^n$ ,  $n \geq 2$ , two bounded domains with boundary  $\partial\Omega_0, \partial\Omega_1$  of class  $C^2$ , such that

$$\overline{\Omega}_1 \subset \Omega_0, \quad (2.1)$$

$$\Omega_0, \Omega_1 \text{ are star shaped with respect to } x_0 \in \overline{\Omega}_1. \quad (2.2)$$

Let us assume

$$\Omega = \Omega_0 \setminus \overline{\Omega}_1. \quad (2.3)$$

We set  $m(x) = x - x_0$ ,  $R(x_0) = \max_{x \in \overline{\Omega}} |m(x)|$  and define

$$\Gamma(x_0) = \{x \in \Gamma; m(x) \cdot \nu(x) > 0\} \quad \text{and} \quad \Gamma_*(x_0) = \Gamma \setminus \Gamma(x_0).$$

The following partition of the boundary is chosen

$$\Gamma_0 = \Gamma(x_0), \quad \Gamma_1 = \Gamma_*(x_0).$$

The action in the boundary  $\Sigma$  is assumed to be of the following type

$$y_1 = \begin{cases} v & \text{on } \Sigma_0 = \Gamma_0 \times (0, T) \\ 0 & \text{on } \Sigma \setminus \Sigma_0 = \Gamma_1 \times (0, T) \end{cases},$$

$$\begin{cases} \frac{\partial y_2}{\partial \nu} = w & \text{on } \Sigma_0, \\ y_2 = 0 & \text{on } \Sigma \setminus \Sigma_0. \end{cases}$$

In addition we consider the following hypotheses

$$p = q = 0 \quad \text{on } \Sigma_0. \quad (2.4)$$

We introduce the following Hilbert spaces

$$V = \left\{ u \in (H_0^1(\Omega))^n; \operatorname{div} u = 0 \right\},$$

$$H = \left\{ u \in (L^2(\Omega))^n; \operatorname{div} u = 0, u \cdot \eta = 0 \text{ on } \Gamma \right\},$$

with the structure of internal product and norm induced by  $(H_0^1(\Omega))^n$  and  $(L^2(\Omega))^n$ , respectively. We still consider

$$\mathcal{V} = \left\{ \varphi \in (D(\Omega))^n; \operatorname{div} \varphi = 0 \right\},$$

$$X = \left\{ \varphi \in (H^1(\Omega))^n; \operatorname{div} \varphi = 0, \varphi = 0 \text{ on } \Gamma_1 \right\},$$

and

$$Y = \left\{ \varphi \in X; \Delta \varphi \in (L^2(\Omega))^n, \frac{\partial \varphi}{\partial \nu} = 0 \text{ on } \Gamma_0 \right\}.$$

The energy associated with the system (1.1) is given by

$$E(t) = E_1(t) + E_2(t), \quad (2.5)$$

where

$$E_i(t) = \frac{1}{2} \left\{ \sum_{k=1}^n \int_{\Omega} |\nabla y_{ki}(t)|^2 dx + \sum_{k=1}^n \int_{\Omega} |y'_{ki}(t)|^2 dx \right\}, \quad i = 1, 2. \quad (2.6)$$

### 3. Inverse Inequality

Let us consider the following problem

$$\begin{cases} \Phi_1'' - \Delta \Phi_1 = -\nabla p & \text{in } Q \\ \operatorname{div} \Phi_1 = 0 & \text{in } Q \\ \Phi_1 = 0 & \text{on } \Sigma \\ \Phi_1(0) = \Phi_1^0, \Phi_1'(0) = \Phi_1^1 & \text{in } \Omega. \end{cases} \quad (3.1)$$

Lions in [7] showed that the solution  $\Phi_1$  of (3.1) has the hidden regularity  $\frac{\partial u}{\partial \nu} \in (L^2(\Sigma))^n$  and that mapping

$$\{\Phi_1^0, \Phi_1^1\} \mapsto \frac{\partial u}{\partial \nu} \quad (3.2)$$

is continuous from  $V \times H$  in  $(L^2(\Sigma))^n$ .

**Remark 3.1:** Multiplying the equation in (3.1)<sub>1</sub> by  $m \nabla \Phi_1$  and integrating in  $Q$ ,

$$\int_Q \Phi_1'' m \nabla y_1 dx dt - \int_Q \Delta \Phi_1 m \nabla \Phi_1 dx dt = \int_Q (-\nabla p) m \nabla \Phi_1 dx dt.$$

Let us put

$$X = - \int_Q \frac{\partial p}{\partial x_i} m_k \frac{\partial \Phi_{1i}}{\partial x_k} dx dt,$$

with the summation convention of repeated indices. Integrating by parts in  $x_k$  and observing (3.1)<sub>3</sub> comes that

$$\begin{aligned} X &= - \int_0^T \frac{\partial p}{\partial x_i} m_k \Phi_{1i} dt \Big|_{\Gamma} + \int_Q \frac{\partial}{\partial x_k} \left( \frac{\partial p}{\partial x_i} m_k \right) \Phi_{1i} dx dt \\ &= \int_Q \frac{\partial^2 p}{\partial x_k \partial x_i} m_k \Phi_{1i} dx dt + \int_Q \frac{\partial p}{\partial x_i} \frac{\partial m_k}{\partial x_k} \Phi_{1i} dx dt \\ &= \int_Q \frac{\partial^2 p}{\partial x_k \partial x_i} m_k \Phi_{1i} dx dt + n \int_Q \frac{\partial p}{\partial x_i} \Phi_{1i} dx dt. \end{aligned}$$

Now,

$$n \int_Q \frac{\partial p}{\partial x_i} \Phi_{1i} dx dt = n \int_0^T p \Phi_{1i} dt \Big|_{\Gamma} - n \int_Q p \frac{\partial \Phi_{1i}}{\partial x_i} dx dt = -n \int_Q p \operatorname{div} \Phi_1 dx dt = 0.$$

Therefore

$$X = \int_Q \frac{\partial^2 p}{\partial x_k \partial x_i} m_k \Phi_{1i} dx dt.$$

Making integration by parts again, it results in

$$\begin{aligned} X &= \int_0^T \frac{\partial p}{\partial x_k} m_k \Phi_{1i} dt \Big|_{\Gamma} - \int_Q \frac{\partial p}{\partial x_k} \frac{\partial}{\partial x_i} (m_k \Phi_{1i}) dx dt \\ &= - \int_Q \frac{\partial p}{\partial x_k} \frac{\partial m_k}{\partial x_i} \Phi_{1i} dx dt - \int_Q \frac{\partial p}{\partial x_k} m_k \frac{\partial \Phi_{1i}}{\partial x_i} dx dt \\ &= - \int_Q \frac{\partial p}{\partial x_k} \delta_i^k \Phi_{1i} dx dt - \int_Q \frac{\partial p}{\partial x_k} m_k \operatorname{div} \Phi_1 dx dt \\ &= \int_Q p \operatorname{div} \Phi_1 dx dt - \int_Q \frac{\partial p}{\partial x_k} m_k \operatorname{div} \Phi_1 dx dt = 0. \end{aligned}$$

**Lemma 3.1.** *Assume  $q = q(x) \in [C^1(\bar{\Omega})]^n$ . Then, for every solution of (3.1) with data  $\{\Phi_1^0, \Phi_1^1\} \in V \times H$ , the following identity holds:*

$$\begin{aligned} & \frac{1}{2} \sum_{k=1}^n \int_{\Sigma} q_k(x) \cdot \nu_k(x) \left| \frac{\partial \Phi_1}{\partial \nu} \right|^2 d\Sigma \\ &= (\Phi_1'(t), q(x) \nabla \Phi_1) \Big|_0^T dx + \sum_{k=1}^n \int_Q \frac{\partial p}{\partial x_i} q_k \frac{\partial \Phi_{1i}}{\partial x_k} dx dt \\ & \quad + \frac{1}{2} \sum_{k=1}^n \int_Q \frac{\partial q_k}{\partial x_k} \left( |\Phi_1'(x, t)|^2 - |\nabla \Phi_1(x, t)|^2 \right) dx dt + \sum_{j,k=1}^n \int_Q \frac{\partial q_k}{\partial x_j} \frac{\partial \Phi_{1i}}{\partial x_k} \frac{\partial \Phi_{1i}}{\partial x_j} dx dt. \end{aligned}$$

**Lemma 3.2.** *Assume  $T > 2R(x_0)$ . Then the following estimate holds for every solution of (3.1) with data  $\{\Phi_1^0, \Phi_1^1\} \in V \times H$ ,*

$$E_{01} \leq \frac{R(x_0)}{2(T - 2R(x_0))} \int_{\Sigma_0} \left| \frac{\partial \Phi_1}{\partial \nu} \right|^2 d\Sigma. \quad (3.3)$$

In the proof of the Lemmas 3.1 and 3.2 we used the idea of Lions [6] together with the Remark 3.1.

We consider now the homogeneous problem for  $\Phi_2$

$$\begin{cases} \Phi_2'' - \Delta \Phi_2 = -\nabla q & \text{in } Q \\ \operatorname{div} \Phi_2 = 0 & \text{in } Q \\ \frac{\partial \Phi_2}{\partial \nu} = 0 & \text{on } \Sigma_0 \\ \Phi_2 = 0 & \text{on } \Sigma_1 \\ \Phi_2(0) = \Phi_2^0, \Phi_2'(0) = \Phi_2^1 & \text{in } \Omega. \end{cases} \quad (3.4)$$

Similarly to the Remark 3.1, multiplying the equation in (3.4)<sub>1</sub> by  $m\nabla\Phi_2$  and integrating in  $Q$ , we obtain

$$\int_Q \Phi_2'' m \nabla \Phi_2 dx dt - \int_Q \Delta \Phi_2 m \nabla \Phi_2 dx dt = \int_Q (-\nabla q) m \nabla \Phi_2 dx dt = 0. \quad (3.5)$$

**Lemma 3.3.** *Assume  $q \in [W^{1,\infty}(\Omega)]^n$ . Then for every weak solution of the homogeneous problem (3.4) with data  $\{\Phi_2^0, \Phi_2^1\} \in Y \times X$  the following identity holds*

$$\begin{aligned} & \int_{\Sigma_0} q_k \nu_k \left( |\Phi_2'|^2 - |\nabla_\sigma \Phi_2|^2 \right) d\Sigma + \frac{1}{2} \int_{\Sigma_1} q_k \nu_k \left| \frac{\partial \Phi_2}{\partial \nu} \right|^2 d\Sigma \\ &= \left( \Phi_{2i}'(t), q_k \frac{\partial \Phi_{2i}(t)}{\partial x_k} \right) \Big|_0^T + \frac{1}{2} \int_Q \frac{\partial q_k}{\partial x_k} \left( |\Phi_2'|^2 - |\nabla \Phi_2|^2 \right) dx dt \\ & \quad + \int_Q \frac{\partial q_k}{\partial x_j} \frac{\partial \Phi_{2i}}{\partial x_j} \frac{\partial \Phi_{2i}}{\partial x_k} dx dt, \end{aligned}$$

where  $\nabla_\sigma \Phi_2$  denotes the tangential gradient of  $\Phi_2$ .

Let  $\lambda_0^2 > 0$  be the first eigenvalues of the following spectral problem

$$\begin{cases} -\Delta \Phi = \lambda^2 \Phi & \text{in } \Omega \\ \operatorname{div} \Phi = 0 & \text{in } \Omega \\ \frac{\partial \Phi}{\partial \nu} = 0 & \text{on } \Gamma_0 \\ \Phi = 0 & \text{on } \Gamma_1. \end{cases} \quad (3.6)$$

**Lemma 3.4.** *Assume  $T > 2R(x_0) + \frac{(n-1)}{\lambda_0}$ . Then every solution of the (3.4) with data  $\{\Phi_2^0, \Phi_2^1\} \in Y \times X$  verifies*

$$E_{02} \leq \frac{R(x_0)}{2 \left( T - 2R(x_0) - \frac{n-1}{\lambda_0} \right)} \int_{\Sigma_0} |\Phi_2'|^2 d\Sigma. \quad (3.7)$$

The proof of the Lemmas 3.3 and 3.4 were done as in Lions [6] adapted to (3.5).

**Theorem 3.1.** *Let  $\Omega$  be a domain satisfying (2.1)–(2.3) and  $T > 4R(x_0) + \frac{n-1}{\lambda_0}$ . Then for every data,*

$$\{\Phi_1^0, \Phi_1^1\} \in V \times H, \quad \{\Phi_2^0, \Phi_2^1\} \in Y \times X,$$

the solutions  $\Phi_1, \Phi_2$  of the homogeneous system

$$\begin{cases}
\Phi_1' - \Delta\Phi_1 = -\nabla p & \text{in } Q \\
\Phi_2' - \Delta\Phi_2 = -\nabla q & \text{in } Q \\
\operatorname{div} \Phi_1 = 0 & \text{in } Q \\
\operatorname{div} \Phi_2 = 0 & \text{in } Q \\
\Phi_1 = 0 & \text{on } \Sigma \\
\frac{\partial\Phi_2}{\partial\nu} = 0 & \text{on } \Sigma_0 \\
\Phi_2 = 0 & \text{on } \Sigma_1 \\
\Phi_1(0) = \Phi_1^0, \Phi_1'(0) = \Phi_1^1 & \text{in } \Omega \\
\Phi_2(0) = \Phi_2^0, \Phi_2'(0) = \Phi_2^1 & \text{in } \Omega
\end{cases} \quad (3.8)$$

verify

$$E_0 \leq \frac{R(x_0)}{2(T - T(x_0))} \int_{\Sigma_0} \left( \frac{\partial\Phi_1}{\partial\nu} + \Phi_2' \right)^2 d\Sigma. \quad (3.9)$$

**Proof.** From (3.3) and (3.7) we obtain for  $T > 2R(x_0) + \frac{n-1}{\lambda_0}$ ,

$$E_0 \leq \frac{R(x_0)}{2\left(T - 2R(x_0) - \frac{n-1}{\lambda_0}\right)} \int_{\Sigma_0} \left( \left| \frac{\partial\Phi_1}{\partial\nu} \right|^2 + |\Phi_2'|^2 \right) d\Sigma. \quad (3.10)$$

Suppose that the following inequality is verified

$$\left| \int_{\Sigma_0} \frac{\partial\Phi_1}{\partial\nu} \Phi_2' d\Sigma \right| \leq 2E_0. \quad (3.11)$$

Then from (3.10) and (3.11) it follows

$$E_0 \leq \frac{R(x_0)}{2\left(T - 4R(x_0) - \frac{n-1}{\lambda_0}\right)} \int_{\Sigma_0} \left( \frac{\partial\Phi_1}{\partial\nu} + \Phi_2' \right)^2 d\Sigma, \quad (3.12)$$

for  $T > 4R(x_0) + \frac{n-1}{\lambda_0}$ .

To conclude the proof of the theorem, it remains then to verify that (3.11) happens.

In fact, multiplying the equation in (3.8)<sub>1</sub> by  $\Phi_2'$ , and integrating on  $Q$ , we obtain

$$\int_Q (\Phi_1' \Phi_2' + \nabla\Phi_1 \nabla\Phi_2') dxdt - \int_{\Sigma} \frac{\partial\Phi_1}{\partial\nu} \Phi_2' d\Sigma = \int_Q p \operatorname{div} \Phi_2' dxdt - \int_{\Sigma} p \Phi_2' d\Sigma. \quad (3.13)$$

Since  $\Phi_2 \in C([0, T], Y) \cap C^1([0, T], X)$ ,  $p$  satisfies (2.4) and  $\Phi_2 = 0$  on  $\Sigma_1$ , then from (3.13), it follows

$$\int_Q (\Phi_1' \Phi_2' + \nabla\Phi_1 \nabla\Phi_2') dxdt = \int_{\Sigma_0} \frac{\partial\Phi_1}{\partial\nu} \Phi_2' d\Sigma. \quad (3.14)$$

Now, multiplying the equation (3.8)<sub>2</sub> by  $\Phi'_1$ , and integrating in  $Q$ , we get

$$\int_Q (\Phi_2'' \Phi'_1 + \nabla \Phi_2 \nabla \Phi'_1) dxdt = \int_Q q \operatorname{div} \Phi'_1 dxdt - \int_\Sigma q \Phi'_1 d\Sigma.$$

Since  $\Phi_1 \in C([0, T], V) \cap C^1([0, T], H)$ , then

$$\int_Q (\Phi_2'' \Phi'_1 + \nabla \Phi_2 \nabla \Phi'_1) dxdt = 0. \quad (3.15)$$

Adding (3.14) and (3.15) comes

$$\int_Q \frac{d}{dt} (\Phi'_1 \Phi'_2 + \nabla \Phi_1 \nabla \Phi_2) dt dx = \int_{\Sigma_0} \frac{\partial \Phi_1}{\partial \nu} \Phi'_2 d\Sigma,$$

that is,

$$\{(\Phi'_1(t), \Phi'_2(t)) + (\nabla \Phi_1(t), \nabla \Phi_2(t))\}|_0^T = \int_{\Sigma_0} \frac{\partial \Phi_1}{\partial \nu} \Phi'_2 d\Sigma.$$

Therefore,

$$\left| \int_{\Sigma_0} \frac{\partial \Phi_1}{\partial \nu} \Phi'_2 d\Sigma \right| \leq 2(E_{01} + E_{02}) = 2E_0,$$

concluding the result. ■

**Corollary 3.1.** *Assume  $\Omega$  as in the Theorem 3.1 and  $T > 4R(x_0) + \frac{n-1}{\lambda_0}$ . Let  $\Phi_1$  and  $\Phi_2$  be two solutions corresponding to the initial data  $\{\Phi_1^0, \Phi_1^1\} \in V \times H$  and  $\{\Phi_2^0, \Phi_2^1\} \in Y \times X$  respectively. If  $\Phi_1$  and  $\Phi_2$  satisfy*

$$\frac{\partial \Phi_1}{\partial \nu} + \Phi'_2 = 0 \quad \text{on } \Sigma_0, \quad \text{then} \quad \Phi_1 = \Phi_2 = 0 \quad \text{in } Q.$$

**Proof.** The proof follows immediately from (3.9). ■

## 4. Simultaneous Controllability

The main result of this work is the following theorem:

**Theorem 4.2.** *Let  $\Omega$  be a bounded domain of the  $\mathbb{R}^n$ ,  $n \geq 2$ , satisfying (2.1)–(2.3) and  $T > 4R(x_0) + \frac{n-1}{\lambda_0}$ . Then for every data  $\{y_1^0, y_1^1, y_2^0, y_2^1\} \in H' \times V' \times (L^2(\Omega))^n \times X'$ , there exists a control  $v \in (L^2(\Sigma_0))^n$ ,*

such that the solution  $\{y_1, y_2\}$  of the system

$$\left\{ \begin{array}{lll} y_1'' - \Delta y_1 = -\nabla p & \text{in} & Q \\ y_2'' - \Delta y_2 = -\nabla q & \text{in} & Q \\ \operatorname{div} y_1 = \operatorname{div} y_2 = 0 & \text{in} & Q \\ y_1 = \begin{cases} v & \text{on} \quad \Sigma_0 \\ 0 & \text{on} \quad \Sigma_1 \end{cases} & & (4.1) \\ \frac{\partial y_2}{\partial \nu} = \frac{\partial v}{\partial t} & \text{on} & \Sigma_0 \\ y_2 = 0 & \text{on} & \Sigma_1 \\ y_1(0) = y_1^0, \quad y_1'(0) = y_1^1 & \text{in} & \Omega \\ y_2(0) = y_2^0, \quad y_2'(0) = y_2^1 & \text{in} & \Omega \end{array} \right.$$

verifies

$$y_1(T) = y_1'(T) = y_2(T) = y_2'(T) = 0.$$

**Proof.** We will apply here the HUM.

First we solve the homogeneous system (3.8) with the initial conditions  $\{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\} \in \mathcal{V} \times \mathcal{V} \times Y \times X$ .

Let us define the quadratic form

$$\|\{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\}\|_F := \left\{ \int_{\Sigma_0} \left| \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \right|^2 \right\}^{\frac{1}{2}}. \quad (4.2)$$

It follows from the Corollary 3.1, that (4.2) defines a norm in  $\mathcal{V} \times \mathcal{V} \times Y \times X$ .

We build the space,

$$F = \overline{\mathcal{V} \times \mathcal{V} \times Y \times X}^{\|\cdot\|_F}.$$

From (3.12) follows the immersion

$$F \hookrightarrow V \times H \times X \times (L^2(\Omega))^n. \quad (4.3)$$

Therefore

$$V' \times H' \times X' \times (L^2(\Omega))^n \hookrightarrow F'$$

with continuous immersion.

Note that

$$\{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\} \in F \Leftrightarrow \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \in (L^2(\Sigma_0))^n. \quad (4.4)$$

On the other hand, from (3.3), the continuity of the application (3.2) and (4.3), we obtain

$$\{\Phi_1^0, \Phi_1^1\} \in V \times H \Leftrightarrow \frac{\partial \Phi_1}{\partial \nu} \in (L^2(\Sigma_0))^2. \quad (4.5)$$

Hence, from (4.4) and (4.5), it follows that

$$\{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\} \in F \Leftrightarrow \left\{ \begin{array}{l} \{\Phi_1^0, \Phi_1^1\} \in V \times H \\ \text{and} \\ \Phi_2' \in (L^2(\Sigma_0))^n. \end{array} \right.$$



Thus, we consider the norm

$$\|\{\Phi_2^0, \Phi_2^1\}\|_G := \left\{ \int_{\Sigma_0} |\Phi_2'|^2 d\Sigma \right\}^{\frac{1}{2}},$$

and the Hilbert space

$$G = \overline{Y \times X}^{\|\cdot\|_G}.$$

From (3.7), it follows

$$G \hookrightarrow X \times (L^2(\Omega))^n.$$

Therefore,

$$F = V \times H \times G$$

and

$$F' = V' \times H' \times G'.$$

We consider the following backward system

$$\begin{cases} \Psi_1'' - \Delta \Psi_1 = -\nabla p & \text{in } Q \\ \Psi_2'' - \Delta \Psi_2 = -\nabla q & \text{in } Q \\ \operatorname{div} \Psi_1 = \operatorname{div} \Psi_2 = 0 & \text{in } Q \\ \Psi_1 = \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' & \text{on } \Sigma_0 \\ \Psi_1 = 0 & \text{on } \Sigma_1 \\ \frac{\partial \Psi_2}{\partial \nu} = \frac{\partial}{\partial t} \left( \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \right) & \text{on } \Sigma_0 \\ \Psi_2 = 0 & \text{on } \Sigma_1 \\ \Psi_1(T) = \Psi_1'(T) = \Psi_2(T) = \Psi_2'(T) = 0 & \text{in } \Omega, \end{cases} \quad (4.6)$$

where  $\frac{\partial}{\partial t} \left( \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \right)$  is taken in the following sense

$$\left\langle \frac{\partial}{\partial t} \left( \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \right), v \right\rangle = - \int_{\Sigma_0} \left( \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \right) v' d\Sigma,$$

for all  $v \in H_0^1(0, T; (L^2(\Gamma_0))^n)$ .

Consider now the application

$$\Lambda : F \rightarrow F',$$

defined by

$$\Lambda \{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\} = \{\Psi_1'(0), -\Psi_1(0), \Psi_2'(0), -\Psi_2(0)\}, \quad (4.7)$$

where  $\{\Psi_1, \Psi_2\}$  is the solution of (4.6).

The norm in (4.2) induces in  $\mathcal{V} \times \mathcal{V} \times Y \times X$  the following inner product

$$\langle \{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\}, \{\xi_1^0, \xi_1^1, \xi_2^0, \xi_2^1\} \rangle_F = \int_{\Sigma_0} \left( \frac{\partial \Phi_1}{\partial \nu} + \Phi_2' \right) \left( \frac{\partial \xi_1}{\partial \nu} + \xi_2' \right) d\Sigma,$$

hence

$$\langle \Lambda \{ \Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1 \}, \{ \Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1 \} \rangle_F = \| \{ \Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1 \} \|_F^2$$

and  $\Lambda$  is an isomorphism between  $F$  and  $F'$ . Therefore, for every  $\{y_1^0, y_1^1, y_2^0, y_2^1\} \in F'$ , there exists only one  $\{\Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1\} \in F$  such that

$$\Lambda \{ \Phi_1^0, \Phi_1^1, \Phi_2^0, \Phi_2^1 \} = \{y_1^1, -y_1^0, y_2^1, -y_2^0\}. \quad (4.8)$$

By (4.7) and (4.8) we conclude that the unique ultra weak solution of (4.6) satisfies (1.1). Then the unique ultra weak solution of (1.1), with control  $v = \frac{\partial \Phi_1}{\partial \nu} + \Phi_2'$  verifies (1.2). ■

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**Resumo.** Neste trabalho estudamos a controlabilidade simultânea para um sistema de equações que representam um modelo da dinâmica de elasticidade para materiais incompressíveis.

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